

Triple Product

Study material by
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Scalar Triple Product. Let $a = a_1 i + a_2 j + a_3 k$, $b = b_1 i + b_2 j + b_3 k$ and $c = c_1 i + c_2 j + c_3 k$, where i, j, k are unit vectors along the three mutually \perp° axes, then the scalar triple product is defined by

$$[abc] = a \cdot (b \times c) = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

Note: (i) $[abc] = [bca] = [cab]$

(ii) $[abc] = -[bac]$, (iii) $a \cdot (b \times c) = (a \times b) \cdot c$

(iv) The scalar triple product gives the volume of the parallelopiped whose sides are represented by the vectors a, b, c .

Vector triple Product.

Let a, b, c be three vectors. Then the vector triple product is defined by $a \times (b \times c) = (a \cdot c)b - (a \cdot b)c$

Note: $(a \times b) \times c = -c \times (a \times b) = (a \cdot c)b - (b \cdot c)a$.

Examples: 1. $[a+b, b+c, c+a] = 2[abc]$

$$\begin{aligned} \text{LHS} &= (a+b) \cdot \{(b+c) \times (c+a)\} = (a+b) \cdot (b \times c + b \times a + c \times a) \\ &= a \cdot b \times c + 0 + 0 + 0 + b \cdot c \times a = [abc] + [bca] = 2[abc] \end{aligned}$$

2. $[a \times b, b \times c, c \times a] = [abc]^2$

$$\begin{aligned} \text{Let } b \times c = \alpha. \text{ Then } (b \times c) \times (c \times a) &= \alpha \times (\alpha \times a) = (\alpha \cdot a)\alpha - (\alpha \cdot \alpha)a \\ &= [bca]\alpha \bullet = [abc]\alpha \end{aligned}$$

$$\text{Now LHS} = (a \times b) \cdot [abc]\alpha = [abc][abc] = [abc]^2.$$

Exercises: 1. Prove $(a \times b) \cdot (c \times d) = (a \cdot c)(b \cdot d) - (a \cdot d)(b \cdot c)$

2. Show that $\alpha \times (\beta \times \gamma) + \beta \times (\gamma \times \alpha) + \gamma \times (\alpha \times \beta) = 0$.

3. Show that the four points whose position vectors are $\alpha, \beta, \gamma, \delta$ are coplanar if $[\alpha\beta\gamma] = [\beta\gamma\delta] + [\gamma\alpha\delta] + [\alpha\beta\delta]$

4. If the four vectors a, b, c, d be such that $a+b+c+d=0$ then show that $\frac{|a|}{[\beta\gamma\delta]} = \frac{-|b|}{[\gamma\delta\alpha]} = \frac{|c|}{[\delta\alpha\beta]} = \frac{-|d|}{[\alpha\beta\gamma]}$

where $\alpha, \beta, \gamma, \delta$ are unit vectors along a, b, c, d respectively.

5. Establish the identities:

$$(i) \alpha = i \times (\alpha \cdot i) + j \times (\alpha \cdot j) + k \times (\alpha \cdot k)$$

$$(ii) [ijk][abc] = \begin{vmatrix} p.a & p.b & p.c \\ q.a & q.b & q.c \\ r.a & r.b & r.c \end{vmatrix},$$

6. Prove that $(\alpha \times \beta) \cdot (\gamma \times \delta) + (\alpha \times \gamma) \cdot (\delta \times \beta) + (\alpha \times \delta) \cdot (\beta \times \gamma) = 0$

Using it to show that $\cos(A+B), \cos(A-B) = \cos^2 A - \sin^2 B$.

7. Show that $|\alpha \times \beta|^2 |\alpha \times \gamma|^2 = -\{(\alpha \times \beta) \cdot (\alpha \times \gamma)\}^2 = |\alpha|^2 [\alpha \cdot \beta]^2$

Differentiation of Vectors

Vector function, limit and continuity: Let P be a variable point on a curve in space whose position vector relative to a fixed origin O be r .

If there exists an independent scalar variable t such that for each value of t in a definite domain, we get a definite position of P , i.e. a unique vector r , then r is called a single valued function of t and is represented as $r = f(t)$.

Let P be the point (x, y, z) then we write

$r = x(t)i + y(t)j + z(t)k$, and the specification of the vector function r defines x, y , and z as functions of t .

A vector function $f(t)$ of the scalar parameter t is said to tend to a limit l as t tends to t_0 if for any $\epsilon > 0$, there exists a $\delta > 0$ such that

$$|f(t) - l| < \epsilon \text{ whenever } 0 < |t - t_0| < \delta.$$

This is expressed as $\lim_{t \rightarrow t_0} f(t) = l$.

A vector function $f(t)$ is said to be continuous at $t = t_0$ if $\lim_{t \rightarrow t_0} f(t) = f(t_0)$.

Derivative: - The derivative of a vector function $r(t)$ of a single parameter t is $\frac{r(t+\Delta t) - r(t)}{\Delta t}$ if exists.

$$r'(t) = \frac{dr}{dt} = \lim_{\Delta t \rightarrow 0} \frac{r(t+\Delta t) - r(t)}{\Delta t}$$

If $r(t) = x(t)i + y(t)j + z(t)k$ then $\frac{dr}{dt} = x'(t)i + y'(t)j + z'(t)k$

- Proposition. Suppose A, B, C are differentiable vector functions of a scalar t and ϕ is a diff. scalar function of u . Then
- (i) $\frac{d}{dt}(A+B) = \frac{dA}{dt} + \frac{dB}{dt}$
 - (ii) $\frac{d}{dt}(A \cdot B) = A \cdot \frac{dB}{dt} + \frac{dA}{dt} \cdot B$
 - (iii) $\frac{d}{dt}(AXB) = A \times \frac{dB}{dt} + \frac{dA}{dt} \times B$
 - (iv) $\frac{d}{dt}(\phi A) = \phi \frac{dA}{dt} + \frac{d\phi}{dt} A$
 - (v) $\frac{d}{dt}[ABC] = [AB \frac{dc}{dt}] + [A \frac{d\phi}{dt} c] + [\frac{da}{dt} BC]$
 - (vi) $\frac{d}{dt}[A \times (B \times C)] = A \times (B \times \frac{dc}{dt}) + A \times (\frac{d\phi}{dt} \times C) + \frac{da}{dt} \times (B \times C).$

Partial derivative of vectors: Suppose A is a vector function of x, y and z , i.e. $A = A(x, y, z)$. The partial derivative of A w.r.t. x is denoted and defined as

$$\frac{\partial A}{\partial x} = \lim_{\Delta x \rightarrow 0} \frac{A(x+\Delta x, y, z) - A(x, y, z)}{\Delta x} \text{ if exists.}$$

The other partial derivatives $\frac{\partial A}{\partial y}$ and $\frac{\partial A}{\partial z}$ are similarly defined. Higher order derivatives can be defined as in calculus.

If A has continuous partial derivatives of the second order at least, we have $\frac{\partial^2 A}{\partial x \partial y} = \frac{\partial^2 A}{\partial y \partial x}$.

Examples 1. If $\alpha = t^2 i - tj + (2t+1)k$ and $\beta = (2t-3)i + j - tk$ then find $\frac{d}{dt}(\alpha \times \frac{d\beta}{dt})$ at $t=2$.

$$\text{we have } \frac{d}{dt}(\alpha \times \frac{d\beta}{dt}) = \alpha \times \frac{d^2 \beta}{dt^2} + \frac{d\alpha}{dt} \times \frac{d\beta}{dt}.$$

$$\text{Now } \alpha = t^2 i - tj + (2t+1)k = 4i - 2j + 5k \text{ at } t=2$$

$$\frac{d\alpha}{dt} = 2ti - j + 2k = 4i - j + 2k \text{ at } t=2$$

$$\beta = (2t-3)i + j - tk = i + j - 2k \text{ at } t=2$$

$$\frac{d\beta}{dt} = 2i - k \text{ at } t=2, \quad \frac{d^2 \beta}{dt^2} = 0 \text{ at } t=2$$

$$\therefore \frac{d}{dt}(\alpha \times \frac{d\beta}{dt}) = \begin{vmatrix} i & j & k \\ 4 & -2 & 5 \\ 0 & 0 & 0 \end{vmatrix} + \begin{vmatrix} i & j & k \\ 4 & -1 & 2 \\ 2 & 0 & -1 \end{vmatrix} = i + 8j + 2k.$$

2. A particle moves along the curve $x = 2t^2, y = t^2 - 4t, z = -t - 5$ where t is time. Find the components of its velocity and acceleration at time $t=1$ in the direction $i - 2j + 2k$.

Soln. velocity $\frac{dr}{dt} = 4t\mathbf{i} + (2t-4)\mathbf{j} - \mathbf{k}$ at $t=1$

Unit vector in direction $\mathbf{i} - 2\mathbf{j} + 2\mathbf{k}$ is $\frac{\mathbf{i} - 2\mathbf{j} + 2\mathbf{k}}{\sqrt{1+4+4}} = \frac{1}{3}\mathbf{i} - \frac{2}{3}\mathbf{j} + \frac{2}{3}\mathbf{k}$

Component of vel. in the given direction is

$$(4\mathbf{i} - 2\mathbf{j} - \mathbf{k}) \cdot \left(\frac{1}{3}\mathbf{i} - \frac{2}{3}\mathbf{j} + \frac{2}{3}\mathbf{k}\right) = 2.$$

Acceleration $\frac{d^2r}{dt^2} = 4\mathbf{i} + 2\mathbf{j}$

Component of Acc. in the given dir. is $(4\mathbf{i} + 2\mathbf{j}) \cdot \left(\frac{1}{3}\mathbf{i} - \frac{2}{3}\mathbf{j} + \frac{2}{3}\mathbf{k}\right) = 0$

3. show that $\mathbf{A} \cdot \frac{d\mathbf{A}}{dt} = |\mathbf{A}| \frac{d}{dt} |\mathbf{A}|^{(A)}$

Soln. since $\mathbf{A} \cdot \mathbf{A} = |\mathbf{A}|^2$, we have $\frac{d}{dt} (\mathbf{A} \cdot \mathbf{A}) = \frac{d}{dt} |\mathbf{A}|^2$

$$\Rightarrow 2\mathbf{A} \cdot \frac{d\mathbf{A}}{dt} = 2|\mathbf{A}| \frac{d|\mathbf{A}|}{dt} \Rightarrow \mathbf{A} \cdot \frac{d\mathbf{A}}{dt} = |\mathbf{A}| \frac{d}{dt} |\mathbf{A}|.$$

Exercises: 1. if a and b are two vector functions of the scalar variable t , then P.T. $a \times \frac{d^2b}{dt^2} - \frac{d^2a}{dt^2} \times b = \frac{d}{dt} (a \times \frac{db}{dt} - \frac{da}{dt} \times b)$.

2. If $\frac{da}{dt} = \alpha \times a$ and $\frac{db}{dt} = \alpha \times b$ then show that

$\frac{d}{dt} (a \times b) = \alpha \times (a \times b)$, where α is a constant vector and a, b are vector functions of scalar variable t .

3. Let F depends on x, y, z, t where x, y , and z depends on t .

$$\text{P.T. } \frac{df}{dt} = \frac{\partial F}{\partial t} + \frac{\partial F}{\partial x} \frac{dx}{dt} + \frac{\partial F}{\partial y} \frac{dy}{dt} + \frac{\partial F}{\partial z} \frac{dz}{dt}.$$

4. suppose a particle moves along a curve $r = (t^3 - 4t)\mathbf{i} + (t^2 + 4t)\mathbf{j} + (8t^2 - 3t^3)\mathbf{k}$. Find the magnitudes of the tangential and normal components of its acceleration when $t=2$.

5. For the curve $r = (2a \cos t, 2a \sin t, bt^2)$, show that $[r \cdot r' \cdot r''] = 8a^2bt$.

6. Find the unit normal to the surface

$$r = a \cos u \sin v \mathbf{i} + a \sin u \sin v \mathbf{j} + a \cos u \mathbf{k}, \quad a > 0$$

7. Let $\frac{d^2A}{dt^2} = 6t\mathbf{i} - 29t^2\mathbf{j} + 48nt\mathbf{k}$. Find A given that

$$A = 2\mathbf{i} + \mathbf{j} \text{ and } \frac{dA}{dt} = -\mathbf{i} - 3\mathbf{k} \text{ at } t=0,$$

Gradient, Divergence, Curl

The vector differential operator del or nable is defined as

$$\nabla = i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z}.$$

Gradient: Let $\phi(x, y, z)$ be a differentiable scalar function at each point (x, y, z) in a certain region of space. Then grad ϕ or $\nabla \phi$ is defined as

$$\nabla \phi = \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \phi = i \frac{\partial \phi}{\partial x} + j \frac{\partial \phi}{\partial y} + k \frac{\partial \phi}{\partial z}.$$

Directional derivative:

Consider a scalar function $\phi(x, y, z)$. Then the directional derivative of ϕ in the direction of a vector a is defined by $\nabla \phi \cdot \frac{a}{|a|}$ where $\frac{a}{|a|}$ is the unit vector in the dir^n of a .

Divergence: Let $v(x, y, z) = v_1 i + v_2 j + v_3 k$ be differentiable at each point (x, y, z) in a region of space. Then the divergence of v , written as $\nabla \cdot v$ or $\operatorname{div} v$ is defined as follows.

$$\begin{aligned}\nabla \cdot v &= \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \cdot (v_1 i + v_2 j + v_3 k) \\ &= \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z}.\end{aligned}$$

Note that $\operatorname{div} v$ is a scalar.

Curl: Let $v(x, y, z) = v_1 i + v_2 j + v_3 k$ be a differentiable vector field. Then the curl or rotation of v , written as $\nabla \times v$, $\operatorname{curl} v$, $\operatorname{rot} v$ is defined as follows:

$$\begin{aligned}\nabla \times v &= \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \times (v_1 i + v_2 j + v_3 k) \\ &= \left(\frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \right) i + \left(\frac{\partial v_1}{\partial z} - \frac{\partial v_3}{\partial x} \right) j + \left(\frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \right) k\end{aligned}$$

Proposition: Suppose A and B are diff. vector functions, and ϕ, ψ are diff. scalar functions. Then the following laws hold:

$$(i) \quad \nabla(\phi + \psi) = \nabla \phi + \nabla \psi, \quad (ii) \quad \nabla \cdot (A + B) = \nabla \cdot A + \nabla \cdot B$$

$$(iii) \quad \nabla \times (A + B) = \nabla \times A + \nabla \times B \quad (iv) \quad \nabla \cdot (\phi A) = (\nabla \phi) \cdot A + \phi (\nabla \cdot A)$$

$$(v) \quad \nabla \times (\phi A) = \nabla \phi \times A + \phi (\nabla \times A), \quad (vi) \quad \nabla \cdot (A \times B) = B \cdot (\nabla \times A) - A \cdot (\nabla \times B).$$

$$2. \quad (i) \quad \nabla \cdot (\nabla \phi) = \nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2}$$

$$(ii) \quad \nabla \times (\nabla \phi) = 0 \quad (iii) \quad \nabla \cdot (\nabla \times A) = 0$$

$$(iv) \quad \nabla \times (\nabla \times A) = \nabla (\nabla \cdot A) - \nabla^2 A.$$

Examples: 1. Find the directional derivative of $\phi = xy^2z + 4x^2z$ at $(-1, 1, 2)$ in the dirⁿ $(2i + j - 2k)$.

$$\begin{aligned} \text{we have } \nabla \phi &= i(y^2z + 8xz) + j(2xyz) + k(xy^2 + 4x^2) \\ &= -14i - 4j + 3k \text{ at } (-1, 1, 2) \end{aligned}$$

The unit vector in the dirⁿ $(2i + j - 2k)$ is $\hat{a} = \frac{2i + j - 2k}{3}$.

$$\therefore \text{Directional derivative} = \nabla \phi \cdot \hat{a} = -\frac{38}{3}.$$

2. Show that $\nabla \phi$ is a vector perpendicular to the surface $\phi(x, y, z) = c$,

Let $r = xi + yj + zk$ be the position vector of any point $P(x, y, z)$ on the surface. Then $dr = idx + jd y + kdz$ lies in the tangent plane to the surface at P .

$$\begin{aligned} \text{Now, } d\phi &= \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz = 0 \\ \Rightarrow (i \frac{\partial \phi}{\partial x} + j \frac{\partial \phi}{\partial y} + k \frac{\partial \phi}{\partial z}) \cdot (idx + jd y + kdz) &= 0 \Rightarrow \nabla \phi \cdot dr = 0 \\ \therefore \nabla \phi &\text{ is perpendicular to } dr \text{ and therefore to the surface.} \end{aligned}$$

3. If the vectors A and B are irrotational, then show that the vector $A \times B$ is solenoidal.

A vector a is said to be solenoidal if $\operatorname{div} a = 0$

Since A and B are irrotational, $\nabla \times A = \nabla \times B = 0$

$$\begin{aligned} \text{Now } \operatorname{div}(A \times B) &= \nabla \cdot (A \times B) = B \cdot (\nabla \times A) - A \cdot (\nabla \times B) \\ &= B \cdot 0 - A \cdot 0 = 0. \end{aligned}$$

4. Suppose $\nabla \times A = 0$. Evaluate $\nabla \cdot (A \times r)$.

Let $A = A_1 i + A_2 j + A_3 k$, $r = xi + yj + zk$. Then

$$A \times r = (xA_2 - yA_3)i + (xA_3 - zA_1)j + (yA_1 - xA_2)k.$$

$$\begin{aligned} \text{and } \nabla \cdot (A \times r) &= \frac{\partial}{\partial x}(xA_2 - yA_3) + \frac{\partial}{\partial y}(xA_3 - zA_1) + \frac{\partial}{\partial z}(yA_1 - xA_2) \\ &= x\left(\frac{\partial A_2}{\partial y} - \frac{\partial A_3}{\partial z}\right) + y\left(\frac{\partial A_3}{\partial z} - \frac{\partial A_1}{\partial x}\right) + z\left(\frac{\partial A_1}{\partial x} - \frac{\partial A_2}{\partial y}\right) \\ &= r \cdot (\nabla \times A) = r \cdot \operatorname{curl} A = 0 \text{ if } \nabla \times A = 0. \end{aligned}$$

5. Prove that $\nabla^2 \left(\frac{1}{r}\right) = 0$.

$$\nabla^2 \frac{1}{r} = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}\right) \left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right).$$

$$\frac{\partial}{\partial x} \left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) = -x \left(\frac{1}{x^2+y^2+z^2}\right)^{3/2}, \quad \frac{\partial^2}{\partial x^2} \left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) = \frac{2x^2-y^2-z^2}{(x^2+y^2+z^2)^{5/2}}$$

$$\text{Similarly, } \frac{\partial^2}{\partial y^2} \left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) = \frac{2y^2-x^2-z^2}{(x^2+y^2+z^2)^{5/2}}, \quad \frac{\partial^2}{\partial z^2} \left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) = \frac{2z^2-x^2-y^2}{(x^2+y^2+z^2)^{5/2}}$$

Then, by addition, we have $\nabla^2 \left(\frac{1}{r}\right) = 0$.

Exercises:

- Find the maximum value of the directional derivative of $\phi = x^2 + z^2 - y^2$ at $(1, 3, 2)$. Find also the direction in which it occurs.
- Show that $\operatorname{curl} u = 0$ if $u = (y^2 + z^2)i + (2xy - 5z)j + (3xz^2 - 5y)k$
- Show that if $r = xi + yj + zk$ and, then (i) $\operatorname{curl} \frac{r}{|r|} = 0$ (ii) $\nabla \cdot \frac{r}{|r|} = \frac{2}{|r|}$ (iii) $\nabla \times \frac{r}{|r|^3} = 0$
- Show that the vector $F = (2x - yz)i + (2y - zx)j + (2z - xy)k$ is irrotational. For this F , find a scalar function ϕ such that $F = \operatorname{grad} \phi$.
- If $\phi = (a \times a) \cdot (a \times b)$ then prove that $\nabla \phi = b \times (a \times a) + a \times (a \times b)$.
- Show that $\nabla f(x, y, z)$ is both irrotational and solenoidal vector if $f(x, y, z)$ satisfies $\nabla^2 f(x, y, z) = 0$.

Vector Integration

Ordinary Integrals of vector valued functions:-

if the vector function $R(t)$ of a scalar variable t be such that $a(t) = \frac{d}{dt} R(t)$

then $\int a(t) dt = R(u) + C$ where C is an arbitrary constant vector independent of t .

Let $a(t) = a_1(t)i + a_2(t)j + a_3(t)k$ be a vector function of a scalar variable t , where $a_1(t), a_2(t)$ and $a_3(t)$ are assumed continuous in a specific interval. Then

$$\int a(t) dt = i \int a_1(t) dt + j \int a_2(t) dt + k \int a_3(t) dt$$

is called an indefinite integral of $a(t)$.

A definite integral of $a(t)$ between the limits $t=a$ and $t=b$ can be written as

$$\int_a^b a(t) dt = [R(u)]_a^b = R(b) - R(a) \text{ if } R'(t) = a(t).$$

Line Integrals :- Let $\mathbf{r}(t) = x(t)i + y(t)j + z(t)k$ be the position vector of $P(x, y, z)$ and suppose $\mathbf{r}(t)$ defines a curve C joining points P_1 and P_2 where $t=t_1$ and $t=t_2$ resp. we assume that C is composed of a finite number of curves for each of which $\mathbf{r}(t)$ has a continuous derivative.

Let $\mathbf{A}(x, y, z) = A_1 \mathbf{i} + A_2 \mathbf{j} + A_3 \mathbf{k}$ be a vector function of position defined and continuous along C . Then the integral of the tangential component of \mathbf{A} along C from P_1 to P_2 written as

$$\int_{P_1}^{P_2} \mathbf{A} \cdot d\mathbf{r} = \int_C \mathbf{A} \cdot d\mathbf{r} = \int_C A_1 dx + A_2 dy + A_3 dz.$$

is an example of a line integral.

If C is a closed curve, the integral around C is denoted as $\oint_C \mathbf{A} \cdot d\mathbf{r} = \oint_C A_1 dx + A_2 dy + A_3 dz$.

Thm: Suppose $\mathbf{A} = \nabla\phi$ everywhere in a region R defined by $[a_1, a_2] \times [b_1, b_2] \times [c_1, c_2]$ and $\phi(x, y, z)$ is single valued and has continuous derivatives in R . Then

(i) $\int_{P_1}^{P_2} \mathbf{A} \cdot d\mathbf{r}$ is independent of the path c in R joining P_1 and P_2

(ii) $\oint_C \mathbf{A} \cdot d\mathbf{r} = 0$ around any closed curve in C in R

In such a case \mathbf{A} is called a conservative vector field and ϕ is its scalar potential.

Surface Integral: Let S be a two-sided surface, where one side is considered arbitrarily the side (usually outer side if S is closed). A unit normal \mathbf{n} to any point of the true side of S is called a positive or outward drawn unit normal.

Associated with the differential of surface area dS , a vector $d\vec{s}$ whose magnitude is ds and whose direction is that of \vec{n} . Then $d\vec{s} = \vec{n} ds$. The integral

$$\iint_S \mathbf{A} \cdot d\vec{s} = \iint_S \mathbf{A} \cdot \vec{n} ds$$

is called the flux of A over S

or a surface integral of A over S .

Other surface integrals are $\iint_S \phi ds$, $\iint_S \phi \vec{n} ds$, $\iint_S \vec{A} \times d\vec{s}$ where ϕ is a scalar function.

Volume Integral: Consider a closed surface in space enclosing a volume V . Then the following denote volume integrals or space integrals:

$$\iiint_V \mathbf{A} dv \text{ and } \iiint_V \phi dv$$

where \mathbf{A} is a vector function and ϕ is a scalar function.

Examples 1. Suppose $\mathbf{F} = (5x^2 + 6y)\mathbf{i} - (3x + 2y^2)\mathbf{j} + 2xz^2\mathbf{k}$
 then evaluate $\int_C \mathbf{F} \cdot d\mathbf{r}$ from $(0,0,0)$ to $(1,1,1)$ along the path C
 given by (i) $x = t, y = t^2, z = t^3$
 (ii) the straight line joining $(0,0,0)$ to $(1,1,1)$.

We have $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C (5x^2 + 6y)dx - (3x + 2y^2)dy + 2xz^2dz$

(i) The points $(0,0,0)$ and $(1,1,1)$ refer to $t=0$ and $t=1$ along
 the curve $x=t, y=t^2, z=t^3$.

$$\begin{aligned}\int_C \mathbf{F} \cdot d\mathbf{r} &= \int_0^1 \{(5t^2 + 6t)dt - (3t + 2t^4)2tdt + 2t \cdot t^6 3t^2 dt\} \\ &= \int_0^1 (5t^2 - 4t^5 + 6t^9)dt = \frac{8}{5}.\end{aligned}$$

(ii) The eqn of the line $\frac{x}{1} = \frac{y}{1} = \frac{z}{1} = t$ say.

$$\begin{aligned}\int_C \mathbf{F} \cdot d\mathbf{r} &= \int_0^1 (5t^2 + 6t)dt - (3t + 2t^4)2tdt + 2t^3 dt \\ &= \int_0^1 (2t^3 + 3t^2 + 3t)dt = \frac{2}{4} + 1 + \frac{3}{2} = 3.\end{aligned}$$

2. Evaluate the surface integral $\iint_S (yz\mathbf{i} + zx\mathbf{j} + xy\mathbf{k})dS$
 where S is the surface of the sphere $x^2 + y^2 + z^2 = 1$ in the
 first octant.

Here $\mathbf{F} = yz\mathbf{i} + zx\mathbf{j} + xy\mathbf{k}$ and $dS = \mathbf{i} dy dz + \mathbf{j} dz dx + \mathbf{k} dx dy$

Thus the integral = $\iint_S (yz dy dz + zx dz dx + xy dx dy)$

$$\begin{aligned}\text{Now } \iint_S yz dy dz &= \int_{y=0}^1 \int_{z=0}^{\sqrt{1-y^2}} yz dy dz = \int_0^1 y dy \left[\frac{z^2}{2} \right]_0^{\sqrt{1-y^2}} \\ &= \frac{1}{2} \int_0^1 y(1-y^2) dy = \frac{1}{8}.\end{aligned}$$

$$\text{Similarly } \iint_S zx dz dx = \iint_S xy dx dy = \frac{1}{8}.$$

$$\text{Required integral} = 3 \times \frac{1}{8} = \frac{3}{8}.$$

3. Let V be the closed region bounded by the surfaces
 $x=0, x=2; y=0, y=6; z=x^2, z=4$ and

$$\mathbf{F} = y\mathbf{i} + 2x\mathbf{j} - z\mathbf{k}. \text{ Find } \iiint_V \nabla \times \mathbf{F} dV$$

$$\text{we have } \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & 2x & -z \end{vmatrix} = \mathbf{k}.$$

$$\text{Therefore } \iiint_V \nabla \times F \, dV = K \int_{x=0}^2 \int_{y=0}^6 \int_{z=x^2}^4 dz \, dy \, dx$$

$$= K \int_{x=0}^2 dx \int_{y=0}^6 (4-x^2) dy = 6K \int_0^2 (4-x^2) dx = 32K.$$

Exercises:

1. If $F = (5xy - 6x^2)i + (2y - 4x)j$ then evaluate $\int_C F \cdot dr$ where C is the curve in the xy -plane given by $y = x^3$ from $(1, 1)$ to $(2, 8)$.
2. Evaluate $\int_C F \cdot dr$, where $F = (x^2 - 3y^2)i + (y^2 - 2x^2)j$ and C is the closed curve in the xy -plane, given by $x = 3 \cos t$, $y = 2 \sin t$, $0 \leq t \leq 2\pi$, C is described in the anti-clockwise sense.
3. Given $A = (yz + 2x)i + xzj + (xy + 2z)k$. Evaluate $\int_C A \cdot dr$ along the curve $x^2 + y^2 = 1$, $z = 1$ in the positive direction from $(0, 1, 1)$ to $(1, 0, 1)$.
4. Evaluate $\iint_S F \cdot n \, ds$, where $F = 6zi - 4j + yk$ and S is that part of the plane $2x + 6y + 3z = 10$ which is located in the first octant.
5. Suppose $A = 4xz i + xy^2 j + 3zk$. Evaluate $\iint_S A \cdot n \, ds$ over the entire surface of the region above the xy -plane bounded by the cone $z^2 = x^2 + y^2$ and the plane $z = 4$.
6. Evaluate $\iint_R \sqrt{x^2 + y^2} \, dy \, dx$ over the region R in the xy -plane bounded by $x^2 + y^2 = 36$.
7. Evaluate $\iiint_V (2xy) \, dV$, where V is the closed region bounded by the cylinder $z = 4 - x^2$ and the planes $x = 0$, $y = 0$, $y = 2$ and $z = 0$.
8. Suppose $F = (2x^2 - 3z)i - 2xyj - 4zk$. Evaluate (a) $\iiint_V \nabla \cdot F \, dV$ and (b) $\iiint_V \nabla \times F \, dV$, where V is the closed region bounded by the planes $x = 0$, $y = 0$, $z = 0$, and $2x + 2y + z = 4$.

Divergence, Stokes' Theorem and Related Integral Theorems

Divergence Thm of Gauss: - Suppose V is the volume bounded by a closed surface S and A is a vector function with continuous derivatives. Then

$$\iiint_V \nabla \cdot A \, dV = \iint_S A \cdot n \, dS = \iint_S A \cdot ds$$

where n is the outward drawn normal to S ,

Stoke's Thm : - Suppose S is an open, two-sided surface bounded by a closed, non-intersecting curve C (simple closed curve), and A is a continuously differentiable vector function. Then

$$\oint_C A \cdot dr = \iint_S (\nabla \times A) \cdot n \, dS$$

where C is traversed in the positive direction,

Ostrogradsky's Thm in the Plane: - Suppose R is a closed region in the xy -plane bounded by a simple closed curve C , and suppose M and N are continuous functions of x and y having continuous derivatives in R . Then

$$\oint_C M \, dx + N \, dy = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx \, dy$$

where C is traversed in the positive (counter-clockwise) direction.

Examples

1. Use divergence thm to evaluate $\iint_S x^3 dy \, dz + \tilde{x}^2 y \, dz \, dx + \tilde{x}^2 z \, dy \, dx$ where S is the closed surface consisting of the cylinder $x^2 + y^2 = 4$ ($0 \leq z \leq 3$) and the circular disc $z=0$ and $z=3$ ($x^2 + y^2 \leq 4$).

The given surface integral is equivalent to the volume integral

$$\text{given by } \iiint [\frac{\partial}{\partial x} (x^3) + \frac{\partial}{\partial y} (\tilde{x}^2 y) + \frac{\partial}{\partial z} (\tilde{x}^2 z)] \, dx \, dy \, dz$$

$$= \int_{z=0}^3 \int_{y=-2}^2 \int_{x=-\sqrt{4-y^2}}^{\sqrt{4-y^2}} 5x^2 \, dx \, dy \, dz = 20 \int_{z=0}^3 \int_{y=0}^2 \int_{x=0}^{\sqrt{4-y^2}} x^2 \, dx \, dy \, dz$$

$$= \frac{60}{3} \int_{y=0}^2 (4-y^2)^{3/2} \, dy = \frac{60}{3} \times 3\pi = 60\pi.$$

2. Verify Stoke's theorem for $\mathbf{F} = (2x-y)\mathbf{i} - yz^2\mathbf{j} - y^2z\mathbf{k}$
 where S is the upper half surface of the sphere $x^2+y^2+z^2=1$
 and C is its boundary.

The boundary C is given by the circle $x^2+y^2=1$.

$$\begin{aligned}\oint_C \mathbf{F} \cdot d\mathbf{r} &= \int_C (2x-y)dx \quad [\text{on } C, z=0, dz=0] \\ &= - \int_0^{2\pi} (2\cos\theta - \sin\theta) \sin\theta d\theta \quad (\text{Put } x=\cos\theta, y=\sin\theta) \\ &= \int_0^{2\pi} \sin^2\theta d\theta = \pi.\end{aligned}$$

Now $\nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2x-y & -yz^2 & -y^2z \end{vmatrix} = \mathbf{k}.$

On the surface of the sphere $x^2+y^2+z^2=1$, $n = x\mathbf{i}+y\mathbf{j}+z\mathbf{k}$,

$$\iint_S (\nabla \times \mathbf{F}) \cdot n \, ds = \iint_S z \, ds = \iint_S \frac{dz}{n \cdot \mathbf{k}} = \iint_S dz = \pi$$

Thus Stoke's theorem is verified.

3. Verify Green's theorem in a plane for $\oint_C (x+ny)dx + nx dy$

where C is the curve enclosing the region bounded by
 $y=x^2$ and $y=x$.

The parabola $y=x^2$ and the line $y=x$ meet at $(0,0)$ and $(1,1)$.

Taking the given integral along $y=x^2$ from $(0,0)$ to $(1,1)$

$$\int_0^1 (x+x^3)dx + x \cdot 2x^2 dx = \left[x^2 + \frac{x^4}{4} \right]_0^1 = \frac{5}{4}.$$

Again, integrating along $y=x$ from $(1,1)$ to $(0,0)$,

$$\int_0^1 2x^2 dx + x dx = \left[\frac{2}{3}x^3 + \frac{x^2}{2} \right]_0^1 = -\frac{7}{6}.$$

Hence the line integral $= \frac{5}{4} - \frac{7}{6} = \frac{1}{12}$.

Now $\iint_S \left(\frac{\partial M}{\partial x} - \frac{\partial N}{\partial y} \right) dx dy$

$$= \iint_S (1-x) dx dy \quad [\text{Since } M = x+ny, N = x]$$

$$= \int_{x=0}^1 \int_{y=x^2}^x (1-x) dy dx$$

$$= \int_0^1 (1-x)(x-x^2) dx = \left[\frac{x^2}{2} - \frac{2x^3}{3} + \frac{x^4}{4} \right]_0^1 = \frac{1}{12}.$$

$$= \int_0^1 (1-x)(x-x^2) dx = \left[\frac{x^2}{2} - \frac{2x^3}{3} + \frac{x^4}{4} \right]_0^1 = \frac{1}{12}.$$

Thus, the theorem is verified.

Exercises: 1. Show that $\iint_S \mathbf{r} \cdot d\mathbf{s} = 3V$ where V is the volume enclosed by the closed surface S and \mathbf{r} has its usual meaning.

2. Prove that $\iiint_V \nabla \phi dV = \iint_S \phi \mathbf{n} dS$.

In particular show that $\iint_S \mathbf{n} dS = 0$.

3. If $\text{grad } \phi = \mathbf{F}$ and $\nabla^2 \phi = 0$, then show that for a closed surface S enclosing the volume V ,

$$\iiint_V \mathbf{F}^2 dV = \iint_S \phi \mathbf{F} \cdot \mathbf{n} dS.$$

4. Verify the divergence theorem for the vector function

$$\mathbf{F} = (x^2 - y^2)\mathbf{i} + (y^2 - z^2)\mathbf{j} + (z^2 - xy)\mathbf{k}$$

taken over the rectangular parallelopiped
 $0 \leq x \leq 1, 0 \leq y \leq 1, 0 \leq z \leq 1$.

5. Use Stoke's thm to show that $\oint_C y dx + z dy + x dz = -2\sqrt{2}\pi a^2$
 where C is given by $x^2 + y^2 + z^2 = 2a^2$, $x+y=2a$.

6. Show that $\frac{1}{2} \oint_C (y dx - x dy)$ represents the area bounded by the closed curve C . Hence show that the area of the ellipse $x = a \cos \theta, y = b \sin \theta$ is πab .

7. Verify Green's thm in a plane for

$$\oint_C \{(3x^2 - 6y^2)dx + (y - 3xy)dy\}$$

where C is the boundary of the region $x=0, y=0, x+y=1$.

8. Verify Stoke's thm for the function $\mathbf{F} = x^2 \mathbf{i} + xy \mathbf{j}$

integrated round the square in the plane $z=0$ whose sides are along the straight lines $x=0, y=0, x=a, y=a$.

9. Verify the divergence thm of Gauss for $\mathbf{F} = 2x^2 \mathbf{i} + y \mathbf{j} - z^2 \mathbf{k}$
 where S is the closed surface consisting of the closed surface of the cylinder $x^2 + y^2 = 16$ between the planes $z=0$ and $z=2$ together with the circular ends of those planes.

10. Use Green's thm in a plane to show that

$$\oint_C \{(x \cos y - xy)dx + (\sin x \cos y)dy\} = 0 \quad \text{where } C \text{ is the circle } x^2 + y^2 = 9 \text{ in the } xy \text{ plane described in the } +ve \text{ sense}$$